

## 1. Ski Jump

### 1.1 Definition of functions and derivatives

```
> restart;
# set up curve and points
y := a*x^4+b*x^3+c*x^2+d*x + e;
dy := diff(y,x);
```

$$y := a x^4 + b x^3 + c x^2 + d x + e$$
$$dy := 4 a x^3 + 3 b x^2 + 2 c x + d$$

### 1.2 Definition of points and tangencies

```
> P1 := [0,80];
P2 := [120,0];
P3 := [140,5];
T1 := [0, 0];
T2 := [120, 0];
```

$$P1 := [0, 80]$$
$$P2 := [120, 0]$$
$$P3 := [140, 5]$$
$$T1 := [0, 0]$$
$$T2 := [120, 0]$$

### 1.3 Substitution to obtain coefficients

```
> eq1 := subs(x=P1[1],y = P1[2];
eq2 := subs(x=P2[1],y = P2[2];
eq3 := subs(x=P3[1],y = P3[2];
eq4 := subs(x=T1[1],dy) = T1[2];
eq5 := subs(x=T2[1],dy) = T2[2];
```

$$eq1 := e = 80$$
$$eq2 := 207360000 a + 1728000 b + 14400 c + 120 d + e = 0$$
$$eq3 := 384160000 a + 2744000 b + 19600 c + 140 d + e = 5$$
$$eq4 := d = 0$$
$$eq5 := 6912000 a + 43200 b + 240 c + d = 0$$

### 1.4 Solve equations to obtain function

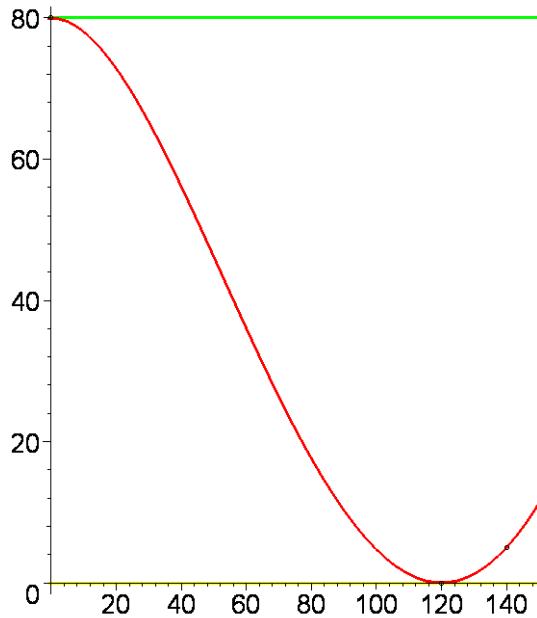
```
> csol := solve({eq1,eq2,eq3, eq4, eq5},{a,b,c,d,e});
> ys := subs(csol,y);
t1 := P1[2] + T1[2]*(x-P1[1]);
t2 := P2[2] + T2[2]*(x-P3[1]);
```

$$csol := \{ d = 0, a = \frac{-13}{42336000}, b = \frac{11}{66150}, c = \frac{-31}{1470}, e = 80 \}$$
$$ys := -\frac{13}{42336000} x^4 + \frac{11}{66150} x^3 - \frac{31}{1470} x^2 + 80$$
$$t1 := 80$$
$$t2 := 0$$

### 1.5 Graph

```
> with(plots):
display({plot([ys, t1, t2],x= -1..150, thickness=3),plot([P1,P2,P3], color=black, style=point, symbol=circle)});
```

Warning, the name changecoords has been redefined



## 2. Cocktail Glass

### 2.1 Definition of functions and constants

```
> restart;
# set up curve and points
y := a*x^6+b*x^5+c*x^4+d*x^3+e*x^2+f*x+g;
dy := diff(y,x);
d2y := diff(y,x,x);
r := 0.375;

y:=a x^6 + b x^5 + c x^4 + d x^3 + e x^2 + f x + g
dy:=6 a x^5 + 5 b x^4 + 4 c x^3 + 3 d x^2 + 2 e x + f
d2y:=30 a x^4 + 20 b x^3 + 12 c x^2 + 6 d x + 2 e
r:=0.375
```

### 2.2 Definition of points and curvature

```
> P1 := [-1.5,3.5];
P2 := [0, 0];
P3 := [1.5,3.5];
T1 := [-1.5, tan(-Pi/6)];
T2 := [1.5, tan(Pi/6)];
T3 := [0, 0];
C1 := [0,2.6667];

P1:=[-1.5, 3.5]
P2:=[0, 0]
P3:=[1.5, 3.5]
T1:=[-1.5, - $\frac{\sqrt{3}}{3}$ ]
T2:=[1.5,  $\frac{\sqrt{3}}{3}$ ]
T3:=[0, 0]
C1:=[0, 2.6667]
```

### 2.3 Substitution for coefficients

```
> eq1 := subs(x=P1[1],y) = P1[2];
eq2 := subs(x=P2[1],y) = P2[2];
eq3 := subs(x=P3[1],y) = P3[2];
eq4 := subs(x=T1[1],dy) = T1[2];
eq5 := subs(x=T2[1],dy) = T2[2];
eq6 := subs(x=T3[1],dy) = T3[2];
eq7 := subs(x=C1[1],d2y) = C1[2];

eq1:=11.390625 a - 7.59375 b + 5.0625 c - 3.375 d + 2.25 e - 1.5 f + g = 3.5
eq2:=g = 0
eq3:=11.390625 a + 7.59375 b + 5.0625 c + 3.375 d + 2.25 e + 1.5 f + g = 3.5
eq4:=-45.56250 a + 25.3125 b - 13.500 c + 6.75 d - 3.0 e + f = - $\frac{\sqrt{3}}{3}$ 
```

$$eq5 := 45.56250 a + 25.3125 b + 13.500 c + 6.75 d + 3.0 e + f = \frac{\sqrt{3}}{3}$$

$$eq6 := f = 0$$

$$eq7 := 2e = 2.6667$$

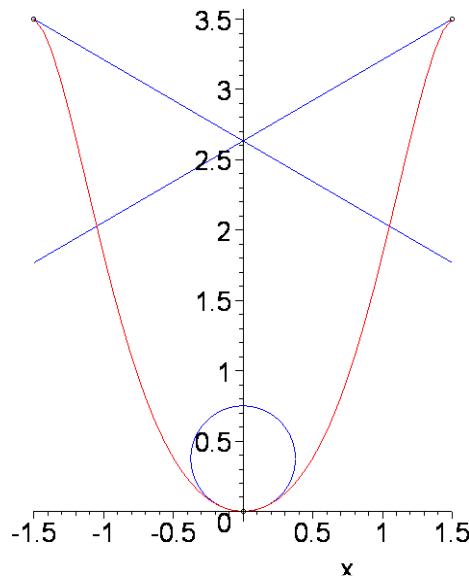
#### 2.4 Solving for equation of curve and olive/cherry

```
> csol := solve({eq1,eq2,eq3,eq4,eq5,eq6,eq7},{a,b,c,d,e,f,g});
> ys := subs(csol,y);
r := 0.375;
bcirc := r-sqrt(r^2-x^2);
tcirc := r+sqrt(r^2-x^2);
t1 := P1[2] + T1[2]*(x-P1[1]);
t2 := P3[2] + T2[2]*(x-P3[1]);

csol := { b = 0., c = 0.8033407009, e = 1.333350000, a = -0.3131478561, g = 0., f = 0., d = 0. }
ys := -0.3131478561 x^6 + 0.8033407009 x^4 + 1.333350000 x^2
r := 0.375
bcirc := 0.375 - sqrt(0.140625 - x^2)
tcirc := 0.375 + sqrt(0.140625 - x^2)
t1 := 3.5 - sqrt(3) (x + 1.5) / 3
t2 := 3.5 + sqrt(3) (x - 1.5) / 3
```

#### 2.5 Graph

```
> with(plots):
display({plot([ys,t1,t2],x=-1.5..1.5, color=[red,blue,blue]),
plot([tcirc,bcirc], x=-r..r, color= blue),
plot([P1,P2,P3], color=black, style=point, symbol=circle)},
scaling = constrained );
Warning, the name changecoords has been redefined
```



#### 2.6 Determination of Curvature

```
> semicircle := sqrt((x)^2 + (z - r)^2);
simplify(diff(semicircle, x, x));
semicircle := sqrt(x^2 + (z - 0.375)^2)
8. (64. z^2 - 48. z + 9.)
(64. x^2 + 64. z^2 - 48. z + 9.)^(3/2)
```

### 3. Cubic Splines

#### 3.1 Definition of functions

```
> restart;
# set up curve and points
p := a*x^3+b*x^2+c*x+d;
dp := diff(p,x);
p := a x^3 + b x^2 + c x + d
```

```

> q := e*x^3+f*x^2+g*x+h;
dq := diff(q,x);

dp := 3 a x2 + 2 b x + c
q := e x3 + f x2 + g x + h
dq := 3 e x2 + 2 f x + g

```

### 3.2 Definition of points and tangencies

```

> P1p := [0,0];
P2p := [1,1];
T1p := [0, 0];
T2p := [1, 0];

P1p := [0, 0]
P2p := [1, 1]
T1p := [0, 0]
T2p := [1, 0]

> P1q := [1,1];
P2q := [2,0];
T1q := [1,0];
T2q := [2,0];

P1q := [1, 1]
P2q := [2, 0]
T1q := [1, 0]
T2q := [2, 0]

```

### 3.3 Substitution to obtain coefficients

```

> eq1 := subs(x=P1p[1],p) = P1p[2];
eq2 := subs(x=P2p[1],p) = P2p[2];
eq3 := subs(x=T1p[1],dp) = T1p[2];
eq4 := subs(x=T2p[1],dp) = T2p[2];

eq1 := d = 0
eq2 := a + b + c + d = 1
eq3 := c = 0
eq4 := 3 a + 2 b + c = 0

> eq5 := subs(x=P1q[1],q) = P1q[2];
eq6 := subs(x=P2q[1],q) = P2q[2];
eq7 := subs(x=T1q[1],dq) = T1q[2];
eq8 := subs(x=T2q[1],dq) = T2q[2];

eq5 := e + f + g + h = 1
eq6 := 8 e + 4 f + 2 g + h = 0
eq7 := 3 e + 2 f + g = 0
eq8 := 12 e + 4 f + g = 0

```

### 3.4 Solve for equations

```

> csolp := solve({eq1,eq2,eq3,eq4},{a,b,c,d});
ps := subs(csolp,p);

csolp := { a = -2, d = 0, c = 0, b = 3 }
ps := -2 x3 + 3 x2

> csolq := solve({eq5,eq6,eq7,eq8},{e,f,g,h});
qs := subs(csolq,q);

csolq := { g = 12, e = 2, f = -9, h = -4 }
qs := 2 x3 - 9 x2 + 12 x - 4

```

### 3.5 Graph

```

> with(plots):
display({plot(ps,x= 0..1, y=-1..1.5),
plot(qs,x= 1..2, y=-1..1.5, color=blue),
plot([P1p,P2p,P2q], color=black, style=point, symbol=circle)},
scaling = constrained );
Warning, the name changecoords has been redefined

```

